

Lecture 10

Independence, Basis and Dimension

Dr. Ralph Chikhany

Recap $A \in \mathbb{R}^{m \times n}$ $Ax = b$, n Variable, m Eq.

rank of Matrix = # pivot variable (in REF)

Free Variable = $n - \text{#pivot variable} = n - r$.

1. if rank = n full column rank matrix.

all the solution is

Free Variables = $n - \text{rank} = 0$

↙ $\vec{x} = \vec{x}_{\text{special}} + \underbrace{\vec{x}_{\text{null}}}_{\vec{x}_{\text{null}} \in \text{Nul}(A)}$

$\text{Nul}(A) = \{ \vec{0} \}$ and $Ax = b$ can 0 solution / 1 solution.

2. if rank $< n$

Free Variable = $n - \text{rank} > 0$

Free Variable ^{ex.} $x_2, x_4 \rightarrow$ Solve all the pivot variable (by x_1, x_3)

$\text{Nul}(A) \neq \{ \vec{0} \}$ and $Ax = b$ can 0 solution / inf solution

3. if rank = m . full row rank Matrix

★ Col(A) = \mathbb{R}^m . ^(Today) which means. $Ax=b$ always have solution (1 / ∞)
for all $b \in \mathbb{R}^m$



Basis of a Vector Space

What is a Basis?

A basis β for a vector space V is a set of vectors $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, such that

(1) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent, and

(2) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ span V . $\text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} = V$

Example Find the basis of \mathbb{R}^2

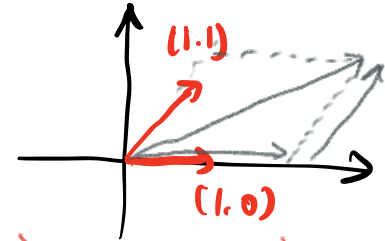
1) $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ $\begin{bmatrix} a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

2) $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ \times $\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

3) $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ \times $\text{span}\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\} \neq \mathbb{R}^2$

4) $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ \checkmark

5) $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix} \right\}$ \times



$$b = x_1 \vec{v}_1 + \dots + x_n \vec{v}_n$$

What is the basis of \mathbb{R}^n

$Ax=b$ always have a solution

- Column vectors of an invertible matrix

n vectors in \mathbb{R}^n and they are linear independent.

Examples

A basis β for a vector space V is a set of vectors $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, such that

- (1) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent, and
- (2) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ span V .

- standard basis for \mathbb{R}^2 is $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

- standard basis for \mathbb{R}^3 is $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

Column Vectors of I_n

⋮

- standard basis for \mathbb{R}^n is $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} \right\}$

Examples

A basis β for a vector space V is a set of vectors $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, such that

- (1) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent, and
- (2) $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ span V .

$\rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$ is invertible!

- another basis for \mathbb{R}^2 is $\beta = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$
- the pivot columns form a basis for Col A
- the nullspace solutions form a basis for Nul A

Vector as a Linear Combination of Basis Vectors

Theorem: If $\vec{v} \in V$, then there is a unique way to write \vec{v} as a linear combination of the basis vectors of V .

$$\text{span}\{\vec{v}_1, \dots, \vec{v}_n\} = V, \quad \vec{v} \in V, \quad \vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

Equation have a unique solution

proof, if $\vec{v} = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n$ (1) we want to proof $c_1 = d_1, \dots, c_n = d_n$

$$\vec{v} = d_1 \vec{v}_1 + \dots + d_n \vec{v}_n \quad (2)$$

$$(1) - (2): \quad \vec{0} = (c_1 - d_1) \vec{v}_1 + \dots + (c_n - d_n) \vec{v}_n$$

by defn of basis. $\vec{v}_1, \dots, \vec{v}_n$ are linear independent.

$c_1 - d_1, \dots, c_n - d_n$ should be the trivial solution

\parallel
 0

\Downarrow

$$c_1 = d_1$$

\parallel
 0

\Downarrow

$$c_n = d_n (!)$$

Example

Nul space.

Find bases for the column and row spaces of $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix}$. row(A) = col(A^T)

span {all row vectors}

Use REF!

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix} \begin{array}{l} R_2 - R_1 \\ R_3 - 3R_1 \end{array} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & -2 & -1 \end{bmatrix} \begin{array}{l} \\ R_3 + R_2 \end{array}$$

$$\sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

x_1 x_2 x_3

REF

$$R_3 = (R_1 + cR_2) - cR_1$$

$$\text{span}(R_1, R_2) = \text{span}(R_1, R_1 + cR_2)$$

$$(R_1, R_2) \rightarrow (R_1, R_2 + cR_1)$$

1) find the Row Space.

only true for Row

Row operation will not change my row space.

$$\text{Row}(A) = \text{Row}(\text{REF})$$

$$\text{basis: } \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \right\}$$

$$\text{rank}(A) = 2 = \dim(\text{Row}(A))$$

2) find the Nul Space.

$$\text{Nul}(A) = \text{Nul}(\text{REF})$$

$$Ax = 0 \Leftrightarrow \text{REF } x = 0 \quad (\text{This is Elimination})$$

x_3 is free

$$x_1 = -x_2 = \frac{1}{2}x_3$$

$$2x_2 + x_3 = 0 \Rightarrow x_2 = -\frac{1}{2}x_3$$

$$= \left\{ \begin{pmatrix} \frac{1}{2}x_3 \\ -\frac{1}{2}x_3 \\ x_3 \end{pmatrix} \mid x_3 \in \mathbb{R} \right\} \leftarrow \text{basis is } \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix}$$

$$x_3 \cdot \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix}$$

$$\dim(\text{Nul}(A)) = 1 = n - r = 3 - 2$$

Example

Nul space.

Find bases for the column and row spaces of $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix}$. row(A) = col(A^T)

Use REF!

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix} \begin{array}{l} R_2 - R_1 \\ R_3 - 3R_1 \end{array} \sim \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & -2 & -1 \end{bmatrix} \begin{array}{l} \\ R_3 + R_2 \end{array}$$

$$\begin{bmatrix} x_1 & x_2 & x_3 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

↑ free

REF

$\dim(\text{Col}(A)) = 2$
 $= \text{rank}(A)$

3) Compute the Column Space

Row operation will change your column using the same way

Ex. $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$

free pivot pivot

third first second

$\begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$

third first second

may be linear dependent

linear combination Relation will not change

Col(A) = span of all column
 = span of all pivot ← basis

Col(REF) basis $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \right\}$

Col(A), basis $\left\{ \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix} \right\}$

Examples

Find a basis for $M_{2 \times 2}$, the vector space of all 2×2 matrices.

$$\left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid a, b, c, d \in \mathbb{R} \right\}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = a \downarrow + b \downarrow + c \downarrow + d \downarrow$$

Find a basis for the vector space of all 3×3 diagonal matrices.

$$\left\{ \begin{pmatrix} a & & \\ & b & \\ & & c \end{pmatrix} \mid a, b, c \in \mathbb{R} \right\} \rightarrow \begin{pmatrix} 1 & & \\ & 0 & \\ & & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & & \\ & 1 & \\ & & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & & \\ & & 1 \end{pmatrix}$$

basis of

$$\left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid \underline{a} + \underline{b} + \underline{c} + d = 0 \right\}$$

{x | condition}

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \begin{pmatrix} 0 & 1 \\ 0 & -1 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 \\ 1 & -1 \end{pmatrix}$$



Dimension of a Vector Space

Meaning of Dimension

The dimension of a vector space V is the number of vectors in a basis β for V .

- $\dim(\mathbb{R}^n) = n$

- For an $m \times n$ matrix A with $\text{rank}(A) = r$. $\rightarrow r$ pivot

- $\dim(\text{Col } A) = r$

- $\dim(\text{Row } A) = r$

$$\dim(\text{Col}(A)) = \dim(\text{Row}(A))$$

- $\dim(\text{Nul } A) = n - r$

↑

#Free Variable = $n - r$

Theorem and Proof Outline

If $\vec{v}_1, \dots, \vec{v}_m$ and $\vec{w}_1, \dots, \vec{w}_n$ are basis for a vector space V , then $m = n$.

Theorem and Full Proof (Optional Reading)

If $\vec{v}_1, \dots, \vec{v}_m$ and $\vec{w}_1, \dots, \vec{w}_n$ are basis for a vector space V , then $m = n$.

Suppose $n > m$

Then $\beta_v = \{\vec{v}_1, \dots, \vec{v}_m\}$ is a basis. Then for $\vec{w}_1 \in V$ we have $\vec{w}_1 = a_{11}\vec{v}_1 + a_{21}\vec{v}_2 + \dots + a_{m1}\vec{v}_m$. Similarly, for $\vec{w}_2 \in V$ we have $\vec{w}_2 = a_{12}\vec{v}_1 + a_{22}\vec{v}_2 + \dots + a_{m2}\vec{v}_m$. In general, any \vec{w}_i can be written as a linear combination of $\vec{v}_1, \dots, \vec{v}_m$.

$$\underbrace{[\vec{w}_1 \vec{w}_2 \dots \vec{w}_n]}_W = \underbrace{[\vec{v}_1 \vec{v}_2 \dots \vec{v}_m]}_V \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Notice that the matrix (call it A) is short and wide since we assumed $n > m$. Thus $A\vec{x} = \vec{0}$ has a nonzero solution.

$$\underbrace{A\vec{x}}_{\# \text{ of } E_1} = \vec{0} \Rightarrow \underbrace{VA\vec{x}}_{\# \text{ of } E_2} = \vec{0} \Rightarrow W\vec{x} = \vec{0}$$

The columns of W are not linearly independent, they can't form a basis (contradiction with the initial assumption)

Suppose $m > n$.

Repeat the same steps and eventually we have:

$$\underbrace{[\vec{v}_1 \vec{v}_2 \dots \vec{v}_n]}_V = \underbrace{[\vec{w}_1 \vec{w}_2 \dots \vec{w}_m]}_W \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1m} \\ b_{21} & b_{22} & \dots & b_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nm} \end{bmatrix}$$

Notice that the matrix (call it B) is short and wide since we assumed $m > n$. Thus $B\vec{x} = \vec{0}$ has a nonzero solution.

$$B\vec{x} = \vec{0} \Rightarrow WB\vec{x} = \vec{0} \Rightarrow V\vec{x} = \vec{0}$$

The columns of V are not linearly independent, they can't form a basis (contradiction with the initial assumption)

Conclusion: The only way to avoid these contradictions is to have $m = n$.



Row Space of a Matrix

Example

Find a basis and the dimension of Col A and Nul A, where

row A

$\text{rank}(A) = 3$

$$A = \begin{bmatrix} 1 & -3 & -6 & 0 \\ 5 & 0 & 0 & 4 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 5 \end{bmatrix} \quad R_2 - 5R_1$$

REF

using Elimination.

$$A \rightsquigarrow \begin{bmatrix} 1 & -3 & -6 & 0 \\ 0 & 15 & 30 & 4 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 5 \end{bmatrix} \xrightarrow{R_3 - \frac{1}{15}R_2} \begin{bmatrix} 1 & -3 & -6 & 0 \\ 0 & 15 & 30 & 4 \\ 0 & 0 & 0 & -\frac{19}{15} \\ 0 & 0 & 0 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & -6 & 0 \\ 0 & 15 & 30 & 4 \\ 0 & 0 & 0 & -\frac{19}{15} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

\leftarrow pivot row
 \leftarrow pivot row
 \leftarrow pivot row

① While doing the row operation, the row space is not changing!!
 the column space will change!

$\text{row}(A) = \text{row}(REF) = \text{span}$

$$\left\{ \begin{pmatrix} 1 \\ -3 \\ -6 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 15 \\ 30 \\ 4 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ -19/15 \end{pmatrix} \right\}$$

pivot row

basis !!

$\text{dim}(\text{row}(A)) = 3$

$= \text{rank}(A)$

② Calculate the Column Space. | linear combination relation still hold.

Ex. in REF $\begin{bmatrix} -6 \\ 30 \\ 0 \\ 0 \end{bmatrix} = 2 \times \begin{bmatrix} -3 \\ 15 \\ 0 \\ 0 \end{bmatrix} + 0 \times \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ in A $\begin{bmatrix} -6 \\ 0 \\ 2 \\ 0 \end{bmatrix} = 2 \times \begin{bmatrix} -3 \\ 0 \\ 1 \\ 0 \end{bmatrix} + 0 \times \begin{bmatrix} 1 \\ 0 \\ 0 \\ 5 \end{bmatrix}$ always holds

Example

Find a basis and the dimension of $\text{Col } A$ and $\text{Nul } A$, where

$$\begin{array}{cccc} x_1 & x_2 & x_3 & x_4 \\ \left[\begin{array}{cccc} 1 & -3 & -6 & 0 \\ 0 & 15 & 30 & 4 \\ 0 & 0 & 0 & -19/15 \\ 0 & 0 & 0 & 5 \end{array} \right] & \text{REF.} & & \end{array}$$

$\uparrow \quad \uparrow \quad \quad \uparrow$
 pivot columns of REF

$$A = \begin{bmatrix} 1 & -3 & -6 & 0 \\ 5 & 0 & 0 & 4 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

$$\begin{aligned} \dim(\text{Col}(A)) &= \dim(\text{Row}(A)) \\ &= \text{rank} = \# \text{ pivots!} \end{aligned}$$

Go back

$$\text{basis of } \text{Col}(A) = \left(\begin{array}{c} 1 \\ 5 \\ 0 \\ 0 \end{array} \right) \quad \left(\begin{array}{c} -3 \\ 0 \\ 1 \\ 0 \end{array} \right) \quad \left(\begin{array}{c} -6 \\ 0 \\ 2 \\ 0 \end{array} \right)$$

!! Go back to matrix A to select Column Vector!!

③ Calculate the null space.

$$\text{Nul}(A) = \text{Nul}(\text{REF})$$

$$\dim(\text{Col}(A)) = 3 = \text{rank}(A)$$

$x_4 = 0$, x_3 is the free variable, $x_2 = -2x_3$, $x_1 = 3x_2 + 6x_3 = 0$

$$\Rightarrow \text{Nul}(\text{REF}) = \text{span} \left\{ \begin{pmatrix} 0 \\ -2 \\ 1 \\ 0 \end{pmatrix} \right\} \quad \begin{pmatrix} 0 \\ -2x_3 \\ x_3 \\ 0 \end{pmatrix} = x_3 \cdot \begin{pmatrix} 0 \\ -2 \\ 1 \\ 0 \end{pmatrix}$$

$$\dim(\text{Nul}(A)) = \overset{n=4}{\downarrow} 4 - 3 = 1$$

Lecture 11

The Four Fundamental Subspaces

Dr. Ralph Chikhany



Strang Sections 3.5 – Dimensions of the Four Subspaces

Course notes adapted from *Introduction to Linear Algebra* by Strang (5th ed) and N. Hammoud's NYU lecture notes.

Thm. $\text{rank}(A) = \text{rank}(A^T)$,

$$\begin{array}{ccc} \parallel & & \parallel \\ \dim(\text{col}(A)) & = & \dim(\text{row}(A^T)) \\ \parallel & & \parallel \\ \dim(\text{row}(A)) & = & \dim(\text{col}(A^T)) \end{array}$$

$$\text{rank}(A) \geq \text{rank}(A \cdot B)$$

$$\text{rank}(B) \geq \text{rank}(A \cdot B)$$

$$\text{col}(A) = \text{row}(A^T)$$

$$\text{row}(A) = \text{col}(A^T)$$

$$\text{rank}(A) = \dim(\text{col}(A))$$

$$\text{rank}(A \cdot B) = \dim(\text{col}(A \cdot B))$$

Claim. $\text{col}(A \cdot B) \subseteq \text{col}(A)$ (is a subspace) ??

by Matrix \times Matrix:

$$A \cdot B = A \begin{bmatrix} \vec{c}_1 & \dots & \vec{c}_p \end{bmatrix} = \begin{bmatrix} A \vec{c}_1 & \dots & A \vec{c}_p \end{bmatrix}$$

\uparrow \uparrow \uparrow
 Column vectors of B $\text{col}(A)$ $\text{col}(A)$

All the column vectors of $A \cdot B$, lies in $\text{col}(A)$

$$\Rightarrow \text{col}(A \cdot B) \subseteq \text{col}(A)$$

$$\dim(\text{col}(A \cdot B)) \leq \dim(\text{col}(A))$$

$$\text{rank}(A \cdot B)$$

$$\text{rank}(A)$$



Matrix Subspaces

The Subspaces Associated with a Matrix

$\mathbb{R}^{m \times n}$

Consider an $m \times n$ matrix $A = [\vec{a}_1 \quad \vec{a}_2 \quad \dots \quad \vec{a}_n]$, where $\vec{a}_i \in \mathbb{R}^m$ ($1 \leq i \leq n$).

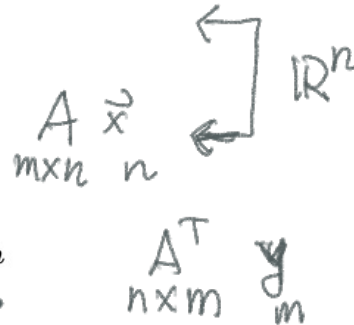
Then, the four fundamental subspaces associated with A are:

→ (1) The column space $\text{Col } A = \text{span}\{\text{pivot columns}\} \subset \mathbb{R}^m$

(2) The row space $\text{Row } A = \text{Col } A^T \subset \mathbb{R}^n$

(3) The nullspace $\text{Nul } A = \{\vec{x} \mid A\vec{x} = \vec{0}\} \subset \mathbb{R}^n$

→ (4) The left nullspace $\text{Nul } A^T = \{\vec{y} \mid A^T\vec{y} = \vec{0}\} \subset \mathbb{R}^m$



both
 \mathbb{R}^m

The Subspaces Associated with a Matrix

Consider an $m \times n$ matrix $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$, where $\vec{a}_i \in \mathbb{R}^m$ ($1 \leq i \leq n$).

Then, the four fundamental subspaces associated with A are:

(1) The column space $\text{Col } A = \text{span}\{\text{pivot columns}\} \subset \mathbb{R}^m$

(2) The row space $\text{Row } A = \text{Col } A^T \subset \mathbb{R}^n$

(3) The nullspace $\text{Nul } A = \{\vec{x} \mid A\vec{x} = \vec{0}\} \subset \mathbb{R}^n$

(4) The left nullspace $\text{Nul } A^T = \{\vec{y} \mid A^T\vec{y} = \vec{0}\} \subset \mathbb{R}^m$

If A is an $m \times n$ matrix with rank r , then

(1) $\dim(\text{Col } A) = r$

(2) $\dim(\text{Row } A) = r$

(3) $\dim(\text{Nul } A) = n - r$
Handwritten notes: $Ax=b$, m Eq, n Var, # free var $n-r$

(4) $\dim(\text{Nul } A^T) = m - r$
Handwritten notes: $A^T y=b$, n Eq, m Var, # free var $m-r$

$$\text{Col}(A), \text{Nul}(A^T) \subseteq \mathbb{R}^m$$

$$\dim(\text{Nul}(A^T)) + \dim(\text{Col}(A)) = m$$

$$\text{Row}(A), \text{Nul}(A) \subseteq \mathbb{R}^n$$

$$\dim(\text{Nul}(A)) + \dim(\text{Row}(A)) = n$$

$$A \mathbf{x} = \begin{bmatrix} \vec{r}_1 \cdot \mathbf{x} \\ \vec{r}_2 \cdot \mathbf{x} \\ \vdots \\ \vec{r}_m \cdot \mathbf{x} \end{bmatrix} = \begin{bmatrix} r_{11}x_1 + r_{12}x_2 + \dots + r_{1n}x_n \\ r_{21}x_1 + r_{22}x_2 + \dots + r_{2n}x_n \\ \vdots \\ r_{m1}x_1 + r_{m2}x_2 + \dots + r_{mn}x_n \end{bmatrix}$$

\vec{r}_i are row vectors

$$A\mathbf{x} = \mathbf{0} \quad \text{means} \quad \underbrace{\vec{r}_1 \cdot \mathbf{x}}_{\vec{r}_1 \perp \mathbf{x}} = \underbrace{\vec{r}_2 \cdot \mathbf{x}}_{\vec{r}_2 \perp \mathbf{x}} = \dots = \underbrace{\vec{r}_m \cdot \mathbf{x}}_{\vec{r}_m \perp \mathbf{x}} = 0$$

$\text{Nul}(A)$ is all the vector \vec{x} that is orthogonal

to \wedge the row vectors = f A
 all ↑↑ ($\vec{r}_1 \dots \vec{r}_m$)
 row space

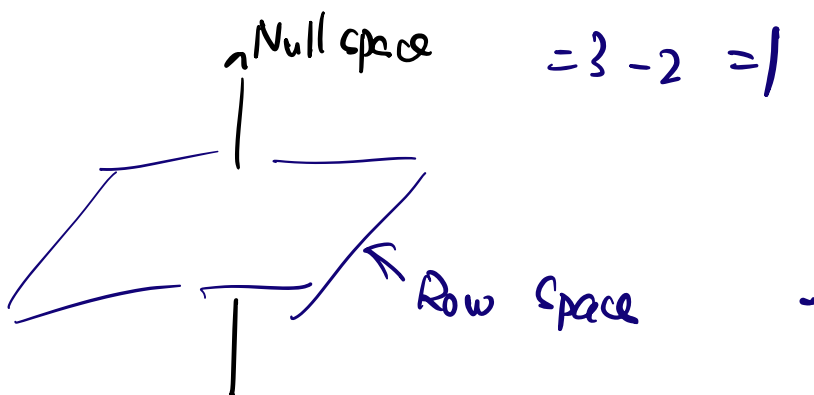
$\text{Nul}(A^T)$ is all the vector \vec{x} that is orthogonal

to \wedge the column vectors = f A
 all ↑↑
 column space

in \mathbb{R}^3 , row space is a plane $\dim(\text{row}) = 2$

$$\dim(\text{Nul}) = \dim(\text{all vectors orthogonal to row space})$$

$$= 3 - 2 = 1$$



Example

Find a basis and dimension of the four fundamental subspaces of

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 & 7 \\ 0 & 0 & 0 & 1 & 2 \\ 1 & 3 & 5 & 1 & 9 \end{bmatrix}.$$

Example

Find a basis and dimension of the four fundamental subspaces of

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 & 7 \\ 0 & 0 & 0 & 1 & 2 \\ 1 & 3 & 5 & 1 & 9 \end{bmatrix}.$$

Example

Find a basis and dimension of the four fundamental subspaces of

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 & 7 \\ 0 & 0 & 0 & 1 & 2 \\ 1 & 3 & 5 & 1 & 9 \end{bmatrix}.$$

Example

Find a basis and dimension of the four fundamental subspaces of

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 & 7 \\ 0 & 0 & 0 & 1 & 2 \\ 1 & 3 & 5 & 1 & 9 \end{bmatrix}.$$



Orthogonality

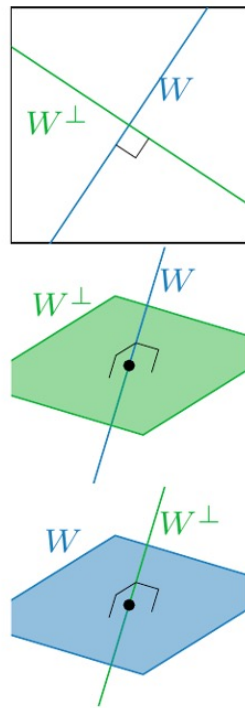
Orthogonal Subspaces

Two subspaces V and W of a vector space are orthogonal if every vector $\vec{v} \in V$ is orthogonal to every vector $\vec{w} \in W$. That is,

$$\vec{v}^T \vec{w} = 0 \quad \text{for all } \vec{v} \in V \text{ and all } \vec{w} \in W.$$

Every vector $\vec{x} \in \text{Nul } A$ is orthogonal to every row of A .
Thus, $\text{Nul } A$ and $\text{Row } A$ are orthogonal subspaces of \mathbb{R}^n .

Every vector $\vec{y} \in \text{Nul } A^T$ is orthogonal to every column of A .
Thus, $\text{Nul } A^T$ and $\text{Col } A$ are orthogonal subspaces of \mathbb{R}^m .



The Fundamental Theorem of Linear Algebra

Let A be an $m \times n$ matrix with rank r .

- $\dim(\text{Col } A) = r$
- $\dim(\text{Row } A) = r$
- $\dim(\text{Nul } A) = n - r$
- $\dim(\text{Nul } A^T) = m - r$
- $(\text{Nul } A)^\perp = \text{Row } A$
- $(\text{Nul } A^T)^\perp = \text{Col } A$